

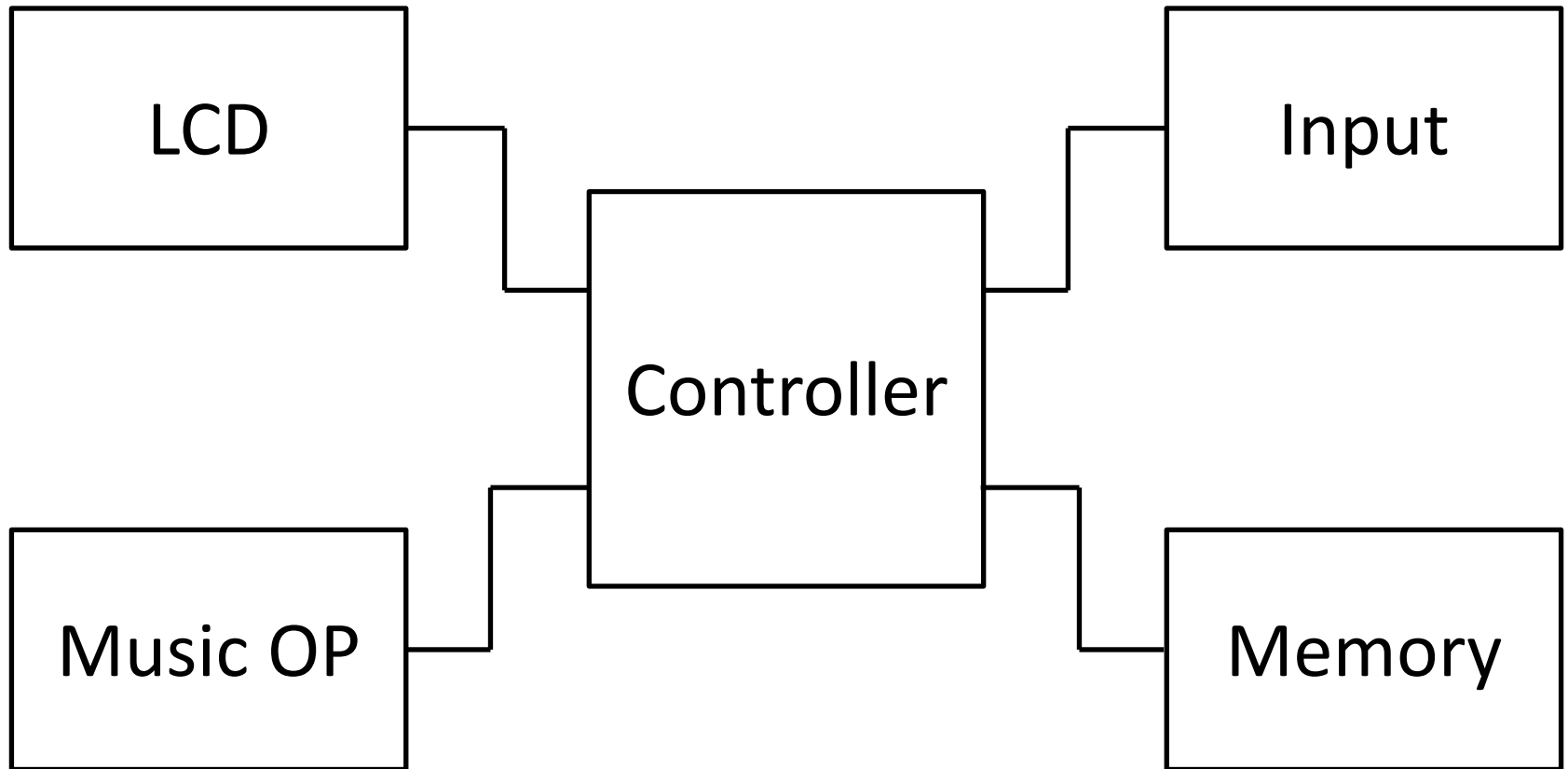
Introduction to Embedded Systems

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Embedded Systems

- Layman definition: Gadgets and devices
- Technical definition: Self-controlled devices
- Usually, such systems consist of I/O (input/output) devices such as LCDs, keypads, etc. and other devices like EEPROM (for storing data) connected to a central controlling device.

Example: MP3 Player



The MicroController (μC)

- Why “micro”?
- Larger controllers are available too: processors that run computers are an example.
- A microcontroller is essentially a mini-computer inside a single IC.

The Computer – μ C analogy

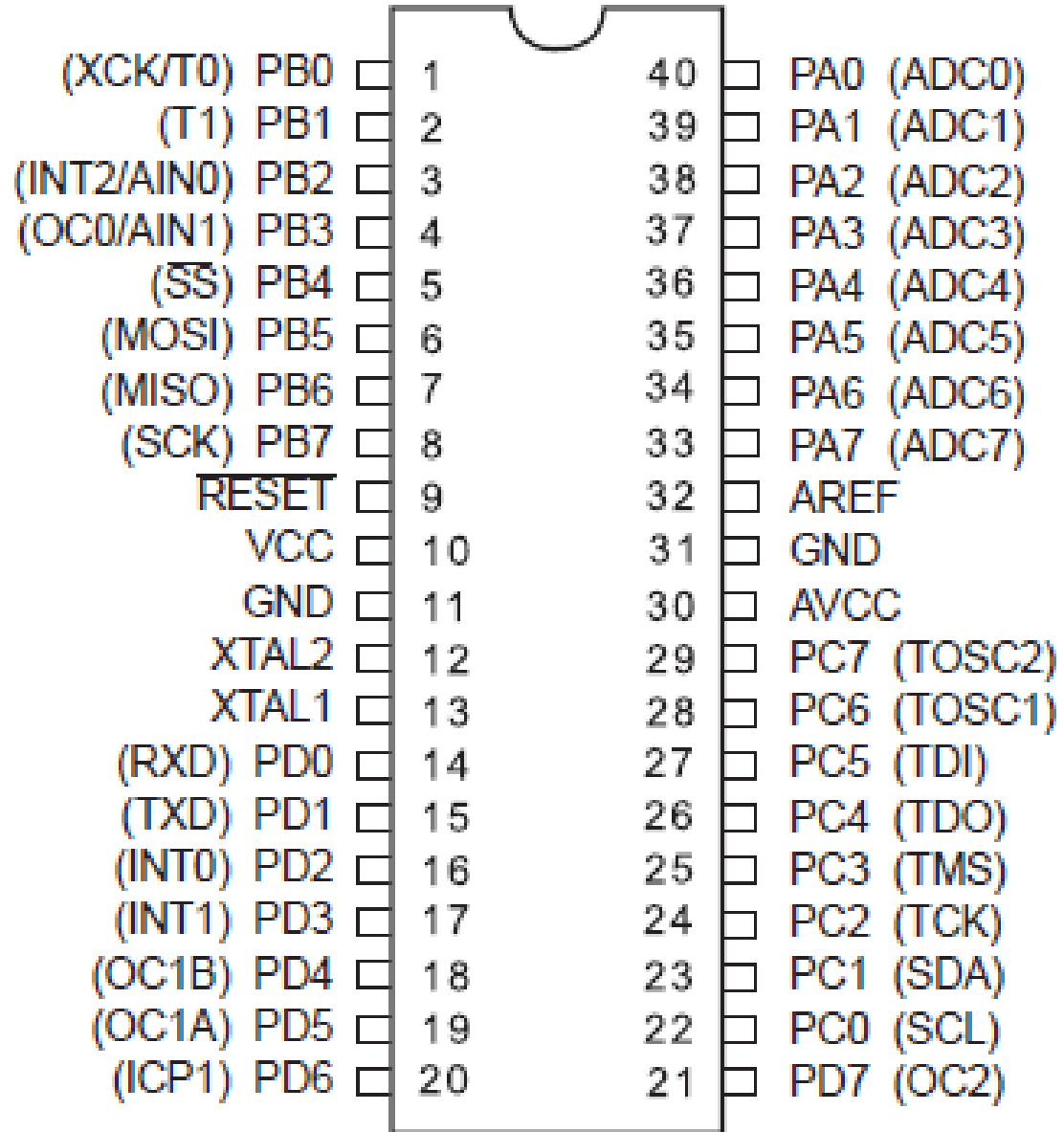
- Inside the CPU, the main components are the processor, RAM, hard disk and I/O.
- The microcontrollers has all the analogous components inside a single IC: the processor core, RAM, EEPROM (hard disk).
- I/O is present in the form of the pins of a microcontroller.

Microcontroller(s)

- Multiple microcontrollers available in the market.
- Vendors include Atmel, Intel, ARM, Cypress, etc.
- We will use Atmel ATmega microcontrollers because they are cheap, easy to use and powerful.

The ATmega16

- 40 pin IC.
- 32 pins for I/O.
- 8 pins reserved.
- I/O pins divided into 4 groups of 8 pins, called ports.
- Ports labeled as A, B, C and D.



How does a microcontroller work?

- Just like a computer, a microcontroller executes a program.
- After the program is finished, nothing happens.
- The program for a microcontroller is written in C language (although other languages are possible).

Some C operators

- | is bitwise OR.

Eg. $10100111 \mid 11000101 = 11100111$

- & is bitwise AND.

Eg. $10100111 \& 11000101 = 10000101$

- ~ is bitwise NOT.

Eg. $\sim 10100110 = 01011001$

- << is shift left. >> is shift right.

Sample C program for a μC

```
int main(){  
    return 0;  
}
```

I/O

- Input / Output is via special variables called “registers”.
- Registers are actual hardware memory locations inside the μC . Their names and sizes are predefined.
- When we assign a value to these registers in the program, the actual value in the hardware changes.
- These values can be changed multiple times at any point in the program.

Example Register Manipulation

```
#include <...>

int main(){
    int i;
    for(i=0;i<10;i++){
        REG1 = i;
    }
    return 0;
}
```

I/O Registers

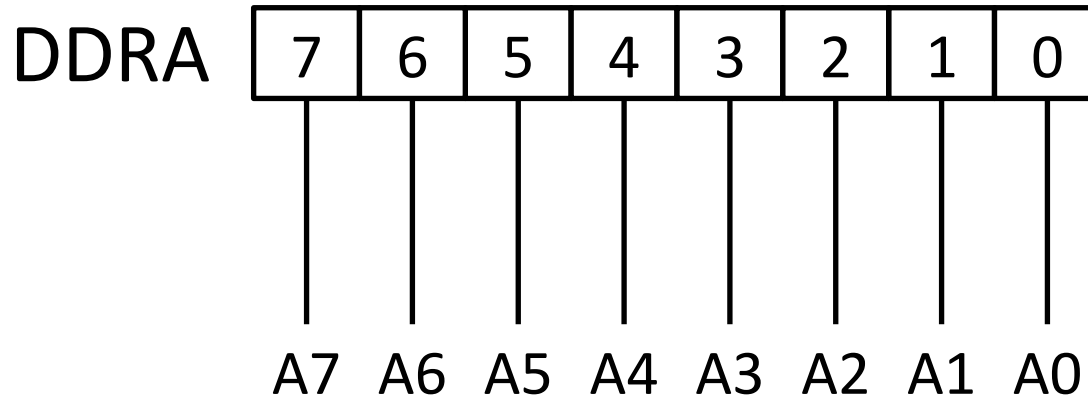
- There are 3 registers that control the I/O pins: **DDR**, **PORT** and **PIN**.
- Each port has it's own registers. Hence, port A has registers **DDRA**, **PORTA**, **PINA**; port B has registers **DDRB**, **PORTB**, **PINB**; and so on.
- **DDR**, **PORT** and **PIN** serve different functions.

DDR (Data Direction Register)

- **DDR** decides whether the pins of a port are input pins or output pins.
- If the pin is input, then the voltage at that pin is undecided until an external voltage is applied.
- If the pin is output, then the voltage at that pin is fixed to a particular value (5V or 0).

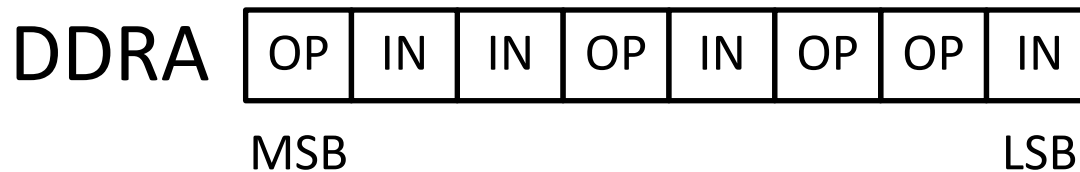
Setting Register Values

- **DDR** is an 8 bit register. Each bit corresponds to a particular pin on the associated port.
- For example, the MSB on **DDRA** corresponds to the pin A7.



Interpretation of DDR values

- If a bit on the **DDR** register is 0, then the corresponding pin on the associated port is set as input.
- Similarly, if the bit is 1, then the pin is set as output.
- Example: if DDRA = 0b10010110, then:



PORT Register

- **PORT** is also an 8 bit register. The bits on the **PORT** register correspond to the pins of the associated port in the same manner as in the case of the **DDR** register.
- **PORT** is used to set the output value.
- If the pin is set as output, then a **PORT** value of 1 will set voltage at that pin to 5V. If **PORT** value is 0, then voltage is set to 0.

Pull up / Pull down

- What if we try to set the **PORT** value of a pin that is configured as input?
- A separate purpose is served: that of pull up or pull down.
- When an input pin is connected by a wire to some specific voltage, it's voltage also becomes that same value.

Pull up / Pull down

- But, when the input pin is left free, it's voltage value is undecided. This is bad.
- To prevent this, a “default” value is assigned. This value can be either 5V or 0, and is of consequence only when the pin is unconnected.
- The **PORT** value becomes this “default” value.
- If “default” value is 0, then pin is pulled down. If it is 5V, then it is pulled up.

PIN register

- **PIN** is a register whose value can be read, but cannot be changed inside the program.
- It gives the value of the actual voltage at a particular pin. 5V corresponds to 1, and 0 corresponds to 0.

Summary

DDR = 0		DDR = 1	
PORT = 0	PORT = 1	PORT = 0	PORT = 1
Pin is input. If unconnected, PIN is 0.	Pin is input. If unconnected, PIN is 1.	Pin is output, value is 0. PIN is always equal to PORT	Pin is output, value is 5V. PIN is always equal to PORT

Example Program 1

```
#include <avr/io.h>
```

```
int main(){  
    DDRA = 0b11111111; // or 255 or 0xFF  
    while(1){  
        PORTA = PINC;  
    }  
    return 0;  
}
```

Example Program 2

```
#include <avr/io.h>
#include <util/delay.h>

int main(){
    DDRA = 0xFF;
    while(1){
        PORTA = 0xAA;
        _delay_ms(1000);
        PORTA = 0x55;
        _delay_ms(1000);
    }
    return 0;
}
```

Thank you